Date: 2025.10.21

YHT-10LA

SPECIFICATIONS

Symbol	Amended Reason			Pages	Date	Corrector	Amendment No.

Approved by	Checked by	Drawn by	Designed by	Title	YHT-10LA Specifications	
KAMITANI	UTSUGI	YAMAGUCHI	YAMAGUCHI	Drawing No.	C-42-04594	1/11

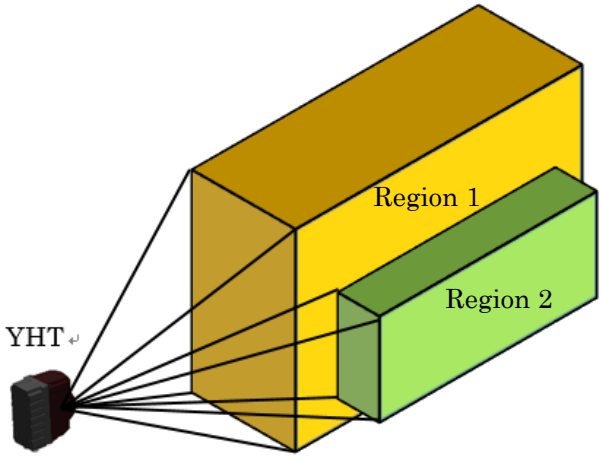
1. General

1.1 Operation principle

YHT scans a field of +40° to -45° vertically × 45° horizontally using a laser beam (λ = 905 nm), determines whether there are any obstacles within the specified installation area, and outputs the information. Small obstacles can be detected by performing interlace operation. Areas can be set in advance using a PC application. Distance, angle data, etc. can be obtained through communication.
This product is class 1 laser product.

1.2 Area

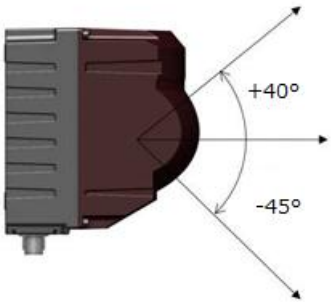
Two detection areas can be monitored simultaneously. In addition, the area can be switched between 3 patterns using the input signal.



2. Structure

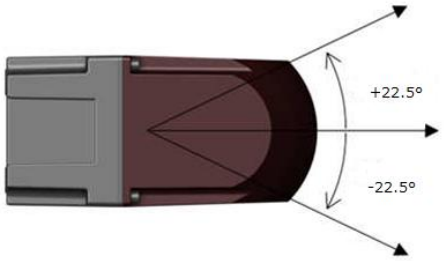
2.1 Scanning range

Vertical scanning range



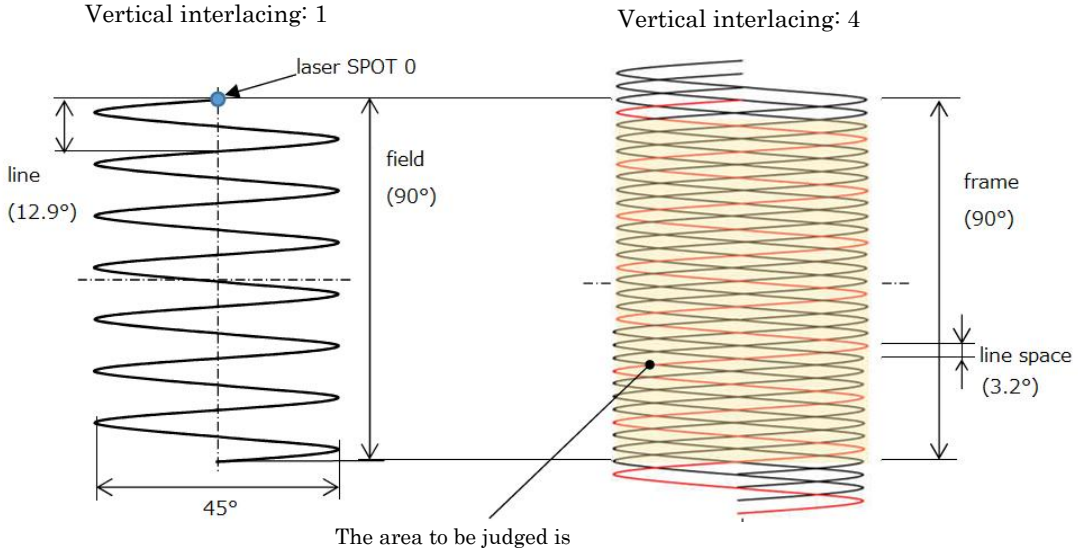
Scanning direction

Horizontal scanning range



2.2 Scanning

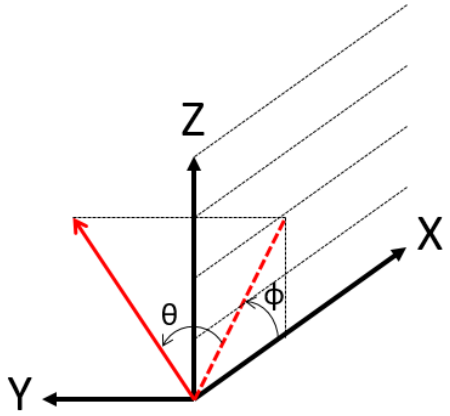
This product uses a motor to scan vertically and a ReM (resonant mirror) to scan horizontally. A scan consists of lines, fields, and frames. One line is 12.9 degrees per cycle, and one field is 90 degrees (7 lines). One frame changes depending on interlace. With interlace settings of 2 or higher, scanning is expanded to 8 lines. Vertical interlace setting: 4 provides 4x higher vertical resolution. When data is acquired via communication, data outside the scan angle range will also be output.



1Frame	MAX 128Field
1Field	7Line
1Line	All 186spot – OFF 28spot
OFF spot No.37,39,41,43,44,45,46,48,49,50,51,53,55,57,	
130,132,134,136,137,138,139,141,142,143,144,146,148,150	

2.2.1 Conversion to orthogonal coordinates

Determine the horizontal angle θ by horizontally scanning the laser with the mirror. The vertical angle of the motor is determined from there. It can be expressed in orthogonal coordinates as shown in the figure below.



3. Disclaimer
   (1) This sensor is not certified for the functional safety.
   (2) This sensor cannot be used for human body detection as per the machinery directives.
   (3) When there is a risk that this sensor is intended for use in mass-destruction weapons, weapons and equipment aimed at killing human beings, and relevant technologies, or when uses for such purposes are clear, sales may be prohibited in accordance with the Foreign Exchange and Foreign Trade Act, and the Export Trade Control Order (Japanese law). Moreover, regarding export of products, the formalities according to laws/Export Trade Control Order are implemented in order to maintain international peace and safety.
   (4) Sensor emits laser for measurement. Sensor's operation may become unstable under the influence of strong light interference or when emitted lights are not reflected back from the object.
   (5) Sensor's operation may become unstable due to rain, snow and fog or due to dust pollution on the optical window.
   (6) Rules and regulations related to safety should be strictly followed by the user when operating the sensor.
   (7) Before using the sensor, make sure to read this specification thoroughly.

4. Specifications

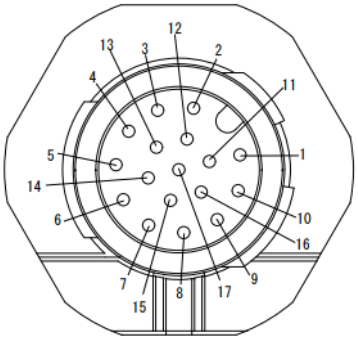
Supply voltage	24VDC ± 10%
Power consumption	5W or less *3
Light source	Semiconductor laser, λ = 905 nm
Laser safety class	Class 1 (IEC60825-1:2014)
Average accuracy by distance	200mm to 10000mm ±40mm *1
Repeated accuracy	σ ＜20mm *1
Detection range and object	Guaranteed value of detection: 200 to 10000mm(Reflectance of 90% 500mm×500mm) *1 300 to 5000mm(Reflectance of 10% 500mm×500mm) *1 Horizontal -10°to -22.5°, Vertical -15° to -45°: 500mm to 3500mm (Reflectance of 10%) Maximum detecting distance: 15m (maximum value of area setting)
Scanning angle	Horizontal direction: 45° Vertical direction: +40° to -45°
Scanning time	17.5ms (varies depending on ReM cycle)
Measurement resolution	1mm
Angular resolution	Vertical direction: 12.9°(interlace setting 16: 0.8°, 32: 0.4°) Horizontal direction: 0.3 to 0.75°(interlace setting 2: 0.15 to 0.375°)
Starting time	Within 60 sec
Output	OUTPUT 5 points: (Photocouple Open collector output DC30V 50mA Maximum residual voltage 2V or less) Region 1 detection: Output is OFF when detected within area Region 2 detection: Output is OFF when detected within area Ready: Output is ON when detection/judgment is possible. Maintenance: Output is OFF due to maintenance request. Malfunction: Output is OFF in failure condition.
Input	INPUT 5 points (Photo-coupler input, Common anode, Input ON current 4 mA) Fitting : Starts fitting area calculation when input is ON Region 1 log input : Enable Region 1 log function when input is ON Region 2 log input : Enable Region 2 log function when input is ON Area pattern switching 1: INPUT for detection area pattern switching Area pattern switching 2: INPUT for detection area pattern switching
Response time	Response time varies depending on the size of the object to be detected and filter settings. Vertical interlace settings 16: 280ms 32: 560ms

Interface	Ethernet 100BASE-TX
Indication lamp	None
Connection method	Power supply, IO: Connector, Communication: connecter
Ambient operating temperature, humidity	-10℃ to +50℃ 85%RH or less (However, dew condensation and freezing should not exist.)
Ambient operating illuminance	100,000 lx or less *2 * If it is directly exposed to strong light such as sunlight, incorrect output may occur.
Storage ambient temperature, humidity	-10℃ to +60℃ 85%RH or less (However, dew condensation and freezing should not exist.) *Since a motor is used, the grease on the bearings becomes hard after long-term storage at low temperatures. Turn on the power and perform warm-up operation.
Vibration resistance	10 to 55 Hz, plural amplitude: 1.5 mm each 2 hours in X, Y and Z directions
Shock resistance	196m/s² (20G) each 10 times in X, Y and Z directions
Compatible standards	(EMI) EN55011: Class A (EMS) EN61000-4-2: B (level 3) EN61000-4-3: A (level 2) EN61000-4-4: A (level 3)
Protective structure	IP67
Weight	800g
Material	Optical window: Polycarbonate, Main body: Aluminum
External Dimension (W × D × H)	62mm×116.5mm×123mm (Main body only)

*1 Indoor environment (fluorescent lamp, 1,000 lux or less)
*2 Detection cannot be guaranteed when direct light (such as sunlight) enters the device.
*3 Please use a power supply with sufficient current capacity.

5. Connection

5.1 Power supply, I/O



M12 Connector 17-pin A-cord / Male

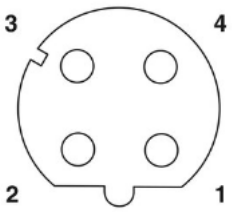
PIN No.	Function	Signal
1	Power supply	+VIN (DC24V)
2	Power supply	-VIN (0V)
3	Output	Region 1 detection
4	Output	Region 2 detection
5	Output	Ready
6	Output	Maintenance
7	Output	Malfunction
8	NC	–
9	NC	–
10	NC	–
11	Input	Fitting
12	Input	Region 1 log input
13	Input	Region 2 log input
14	Input	Area pattern switching 1
15	Input	Area pattern switching 2
16	IO Power supply	COM+
17	IO Power supply	COM-

Please leave unused input lines OPEN or connect them to COM+.
Please leave unused output lines OPEN or connect them to COM-.
Do not connect to NC as there is internal wiring.

Compatible cable model: SAC-17P-1,5-PVC/FS SCO etc.
* Power supply and I/O cables are sold separately.

PIN No.	Wire color	Signal
1	Brown	+VIN (DC24V)
2	Blue	-VIN (0V)
3	White	Region 1 detection
4	Green	Region 2 detection
5	Pink	Ready
6	Yellow	Maintenance
7	Black	Malfunction
8	Gray	–
9	Red	–
10	Purple	–
11	Gray(Pink)	Fitting
12	Red(Blue)	Region 1 log input
13	White(Green)	Region 2 log input
14	Brown(Green)	Area pattern switching 1
15	White(Yellow)	Area pattern switching 2
16	Yellow(Brown)	COM+
17	White(Gray)	COM-

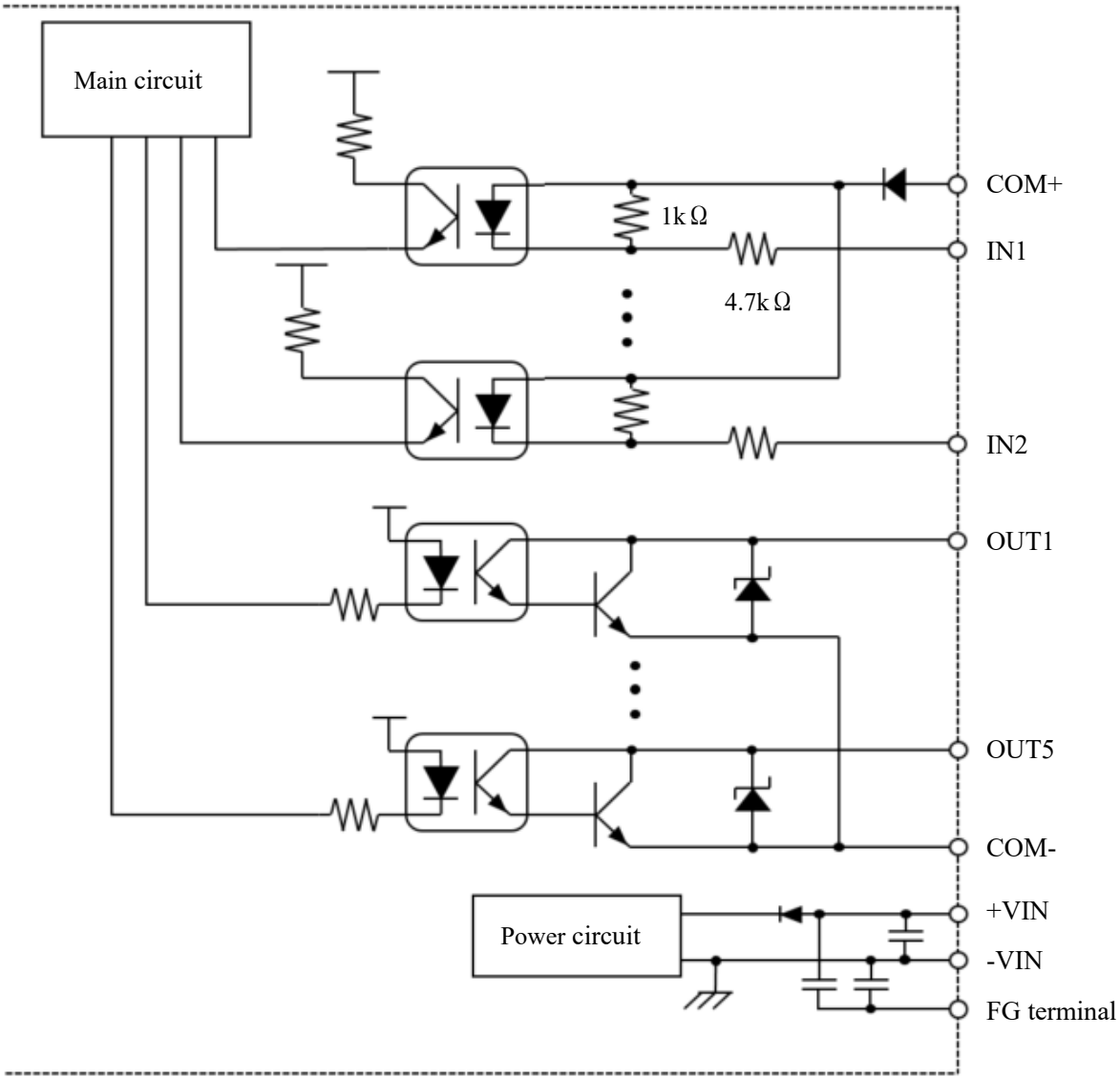
5.2 Ethernet
Compatible Ethernet cable model: NBC-MSD□,0-93E/R4ACSCO etc.
* Ethernet cables are sold separately.



M12 Connector 4-pin D-code / Female

PIN No.	Signal
1	RX+
2	TX+
3	RX-
4	TX-

6. Input/output circuit



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7. Control signal

7.1 Region detection 1/2

Shows the presence or absence of obstacles within the area when the area is set in the application.

7.2 Ready

Outputs when the sensor is performing in judgment state.

7.3 Maintenance

Outputs when the sensor's optical window is dirty. Please set the threshold, delay, output items, etc. in the application.

7.4 Malfunction

Shows the sensor failure status.

7.5 Fitting

This is the input to start calculations in the fitting area. Please input for 20ms or longer

①when the input turns ON , calculations for the area begin.

Judgment stops, and detection output is maintained. Ready turns OFF.

②After area creation completes, Ready turns ON, the area type turns OFF, and it transitions to judgment operation.

③When the input turns OFF, it switches to the teaching area. Area type turns ON.

※If the fitting area cannot be created, it automatically switches to the normal area.

At this time, Ready turns ON and Area type remains ON.

The same applies if there is no data for calculation.

※For details, refer to the YHT Configurator Standard Instruction Manual.

7.6 Region 1/2 Log

Region log is enabled and records logs when switching between obstacle detection and non-detection.

7.7 Area pattern switching 1/2

Switch to a registered area using a combination of two inputs.
There are three types of area patterns that can be set, and the area is selected by the two inputs.
If both inputs are ON, it will become sleep mode.
Returning from sleep mode to judgment state takes the same amount of time as the power supply startup time.

Area pattern	Area pattern switching **1**	Area pattern switching **2**
Pattern 1	OFF	OFF
Pattern 2	ON	OFF
Pattern 3	OFF	ON
Sleep mode	ON	ON

8. Sensor status and output list

Sensor status/output	Area detection	Ready	Maintenance	Malfunction
During start up	OFF	OFF	ON	ON
During waiting for measurement (Loading log etc.)	□	OFF	□	ON
Normal time	Detection: OFF No detection: ON	ON	Error detection: OFF Normal time: ON	ON
During Area switching	□	OFF	□	ON
When detecting light dirt	Detection: OFF No detection: ON	ON	OFF	ON
When detecting heavy dirt	OFF	OFF	OFF	ON
Malfunction	OFF	OFF	□	OFF
Sleep mode	OFF	OFF	□	ON
During Area writing	□	OFF	□	ON
During updating	-	-	-	-

-: Undefined (could be either) ON: Current is flowing
□: Keep previous status OFF: No current is flowing

9. Ethernet setting

9.1 Default value

IP default value: 192.168.0.10
Port No.: 10940 , 10941

9.2 Changing IP

IP changes and initialization are possible using the dedicated application (IP Discovery). For details on installing and operating IP Discovery, please refer to the IP Discovery Instruction Manual (C-41-02603).

* Any attempt to obtain private commands by means such as communication analysis is prohibited. Private commands are commands that are not officially provided by our company and we do not permit their use. Using or obtaining private commands can cause serious problems with system stability and security. We are not responsible for any damages or problems resulting from the use or acquisition of private commands.

10. Revision history

Revision date	Amended No.	Details
2025/10/21	-	First edition